

# Eaton EP-400030

Catalog Number: EP-400030

Eaton DA1 Variable frequency drive, 230 V AC, 3-phase, 24 A, 5.5 kW, IP66/NEMA 4X, Radio interference suppression filter, OLED display, Local controls, UV resistant



Photo is representative

## General specifications

Product Name	Catalog Number
Eaton DA1 Variable frequency drive	EP-400030
Model Code	EAN
DA1-32024FB-B6SO	4015082950125
Product Length/Depth	Product Height
225.5 mm	310 mm
Product Width	Product Weight
210.5 mm	6.6 kg

## Certifications

CE  
 Certified by UL for use in Canada  
 CSA-C22.2 No. 14  
 CUL  
 DNV  
 EAC  
 IEC/EN 61800-3  
 IEC/EN61800-3  
 IEC/EN61800-5  
 RCM  
 RoHS, ISO 9001  
 Safety: EN 61800-5-1: 2003  
 Specification for general requirements:  
 IEC/EN 61800-2  
 UkrSEPRO  
 UL  
 UL 508C  
 UL Category Control No.: NMMS,  
 NMMS7

## Catalog Notes

The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. different duty cycles) are available upon request.

## General

### Cable length

100 m, screened, maximum permissible, Motor feeder  
150 m, unscreened, maximum permissible, Motor feeder  
200 m, screened, with motor choke, maximum permissible, Motor feeder  
300 m, unscreened, with motor choke, maximum permissible, Motor feeder  
C2 ≤ 5 m, Radio interference level, maximum motor cable length  
C3 ≤ 25 m, Radio interference level, maximum motor cable length

### Communication interface

CANopen®, built in  
EtherCAT, optional  
Ethernet IP, optional  
Modbus RTU, built in  
Modbus-TCP, optional  
OP-Bus (RS485), built in  
PROFIBUS, optional  
PROFINET, optional  
BACnet/IP, optional

### Connection to SmartWire-DT

No

### Degree of protection

IP66  
NEMA 4X

### Electromagnetic compatibility

1st and 2nd environments (according to EN 61800-3)

### Fitted with:

Additional PCB protection  
Brake chopper  
Breaking resistance  
Control unit  
IGBT inverter  
Internal DC link  
OLED display  
PC connection  
Radio interference suppression filter  
Local controls

### Frame size

FS4

## Climatic environmental conditions

### Altitude

Max. 1000 m  
Above 1000 m with 1 % derating per 100 m  
Max. 4000 m

### Ambient operating temperature - min

-10 °C

### Ambient operating temperature - max

40 °C

### Ambient operating temperature at 150% overload - min

-10 °C

### Ambient operating temperature at 150% overload - max

40 °C

### Ambient storage temperature - min

-40 °C

### Ambient storage temperature - max

60 °C

### Climatic proofing

< 95 average relative humidity (RH), no condensation, no corrosion

## Main circuit

### Efficiency

96.9 % (η)

### Heat dissipation at current/speed

153 W at 100% current and 0% speed  
197 W at 100% current and 50% speed  
246 W at 100% current and 90% speed  
89 W at 50% current and 0% speed  
112 W at 50% current and 50% speed  
128 W at 50% current and 90% speed  
93 W at 25% current and 50% speed  
72 W at 25% current and 0% speed

### Input current ILN at 150% overload

26.9 A

### Leakage current at ground IPE - max

1.42 mA

### Mains switch-on frequency

## Functions

4-quadrant operation possible

## Mounting position

Vertical

## Product Category

Variable frequency drives

## Protection

Finger and back-of-hand proof, Protection against direct contact (BGV A3, VBG4)

## Protocol

CAN

EtherNet/IP

MODBUS

Other bus systems

PROFIBUS

PROFINET IO

TCP/IP

BACnet/IP

## Safety function/level

STO (Safe Torque Off, SIL3, PLe Cat 3)

## Suitable for

Branch circuits, (UL/CSA)

## Radio interference class

C1: for conducted emissions only

Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments

C2, C3: depending on the motor cable length, the connected load, and ambient conditions.

Maximum of one time every 30 seconds

## Mains voltage - min

180 V

## Mains voltage - max

264 V

## Operating mode

Optional: Vector control with feedback (CLV)

Sensorless vector control (SLV)

Speed control with slip compensation

U/f control

## Output frequency - min

0 Hz

## Output frequency - max

500 Hz

## Output voltage (U<sub>2</sub>)

240 V AC, 3-phase

230 V AC, 3-phase

## Overload current I<sub>L</sub> at 150% overload

36 A

## Rated control supply voltage

10 V DC (U<sub>s</sub>, max. 10 mA)

## Rated frequency - min

48 Hz

## Rated frequency - max

62 Hz

## Rated operational power at 220/230 V, 50 Hz, 1-phase

5.5 kW

## Rated operational voltage

240 V AC, 3-phase

230 V AC, 3-phase

## Resolution

0.1 Hz (Frequency resolution, setpoint value)

## Short-circuit protection rating

40 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring

## Starting current - max

200 %, I<sub>H</sub>, max. starting current (High Overload), for 4 seconds every 40 seconds, Power section

### Supply frequency

50/60 Hz

### Switching frequency

8 kHz, 4 - 24 kHz adjustable (audible), fPWM, Power section, Main circuit

### System configuration type

AC supply systems with earthed center point

### Voltage rating - max

240 VAC

## Motor rating

Assigned motor current  $I_M$  at 220 - 240 V, 60 Hz, 150% overload  
22 A

Assigned motor current  $I_M$  at 230 V, 50 Hz, 150% overload  
19.6 A

Assigned motor power at 230/240 V, 60 Hz, 1-phase  
7.5 HP

## Apparent power

Apparent power at 230 V  
9.56 kVA

Apparent power at 240 V  
9.98 kVA

## Braking function

### Braking resistance

20  $\Omega$

### Braking torque

Max. 30 % MN, Standard - Main circuit

Max. 100 % of rated operational current  $I_e$ , variable, DC - Main circuit

Max. 100 % of rated operational current  $I_e$  with external braking resistor - Main circuit

### Switch-on threshold for the braking transistor

390 VDC

## Control circuit

### Number of inputs (analog)

2

### Number of inputs (digital)

5

### Number of outputs (analog)

2

### Number of outputs (digital)

2

### Number of relay outputs

2 (parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1))

### Rated control voltage ( $U_c$ )

24 V DC (external, max. 100 mA)

## Design verification

### Equipment heat dissipation, current-dependent $P_{vid}$

170.5 W

### Heat dissipation capacity $P_{diss}$

0 W

## Resources

### 3D models

[eaton-EP-400028-drawing.dwg](#)

[eaton-EP-400028-3d-model.stp](#)

### Application notes

Heat dissipation per pole, current-dependent P<sub>vid</sub>

0 W

Static heat dissipation, non-current-dependent P<sub>vs</sub>

0 W

#### 10.2.2 Corrosion resistance

Meets the product standard's requirements.

##### 10.2.3.1 Verification of thermal stability of enclosures

Meets the product standard's requirements.

##### 10.2.3.2 Verification of resistance of insulating materials to normal heat

Meets the product standard's requirements.

##### 10.2.3.3 Resist. of insul. mat. to abnormal heat/fire by internal elect. effects

Meets the product standard's requirements.

#### 10.2.4 Resistance to ultra-violet (UV) radiation

Meets the product standard's requirements.

#### 10.2.5 Lifting

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.2.6 Mechanical impact

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.2.7 Inscriptions

Meets the product standard's requirements.

#### 10.3 Degree of protection of assemblies

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.4 Clearances and creepage distances

Meets the product standard's requirements.

#### 10.6 Incorporation of switching devices and components

Does not apply, since the entire switchgear needs to be evaluated.

#### 10.7 Internal electrical circuits and connections

Is the panel builder's responsibility.

#### 10.8 Connections for external conductors

Is the panel builder's responsibility.

#### 10.9.2 Power-frequency electric strength

Is the panel builder's responsibility.

#### 10.9.3 Impulse withstand voltage

Start, Stopp und Betrieb

Master slave operation

I/O Configuration

Operating Permanent Magnet and Brushless DC Motors

Hoist applications

Dual Rating What exactly does that mean?

Connecting drives to generator supplies

Update DX-COM-STICK3

Equal load sharing with the droop function

Setpoint Setting

Starting, Stopping and Operation

How does the internal motor protection work?

Electromagnetic compatibility (EMC)

PID controller

Access to Parameter Level 2 and 3 Parameter Lock RESET

Use of multiple ramps

Vector Control of Induction Motors

Motor data Motor Protection V/f curves for induction motors

DX-COM-STICK3\_Connection

Dependency of the output current on switching frequency and ambient temperature

Conformal Coating

The OP System Bus - Parameterizing - Control

Closed Loop Vector Control

#### Brochures

[eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-br040001en-en-us.pdf](#)

#### Catalogues

Product Range Catalog Drives Engineering

Drives - Product range catalog

#### Declarations of conformity

[DA-DC-00005013.pdf](#)

[DA-DC-00005022.pdf](#)

#### Installation instructions

[eaton-da1-variable-frequency-drive-il040061zu.pdf](#)

#### Installation videos

PowerXL Variable Frequency Drives DC1 and DA1 - EN

Video PowerXL DA1

#### Manuals and user guides

Is the panel builder's responsibility.

#### 10.9.4 Testing of enclosures made of insulating material

Is the panel builder's responsibility.

#### 10.10 Temperature rise

The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.

#### 10.11 Short-circuit rating

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

#### 10.12 Electromagnetic compatibility

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

#### 10.13 Mechanical function

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

[eaton-da1-variable-frequency-drive-mn040063-en-us.pdf](#)

mCAD model

[eaton-cadenas-front\\_view-p2\\_ip66\\_size3\\_switched\\_front.pra](#)

[eaton-cadenas-path-drives-p2\\_ip66\\_size3\\_switched.3db](#)

[eaton-cadenas-side\\_view-p2\\_ip66\\_size3\\_switched\\_side.pra](#)

#### Multimedia

Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments?

System solutions based on EtherCAT

#### Software, firmware, and applications

[eaton-powerxl-dx-cbl-pc-1m5-usb-driver.zip](#)

[eaton-powerxl-da1-profinet-gsdml-v226.zip](#)

[eaton-powerxl-pcsoftware-drivesconnect-v1501.zip](#)

[eaton-powerxl-da1-swd-codesys-v3-library.zip](#)

[eaton-powerxl-da1-canopen-eds-v250.zip](#)

[eaton-powerxl-da1-ethercat-esi-v310.zip](#)

[eaton-powerxl-da1-canopen-codesys-v3-library.zip](#)

[eaton-powerxl-dx-comstick3-ble-drivers.zip](#)

[eaton-powerxl-da1-profibus-gsd-v216.zip](#)

[eaton-powerxl-da1-profinet-tia-v12-library.zip](#)

[eaton-powerxl-dx-cbl-pc-3m0-usb-driver.zip](#)

[eaton-powerxl-da1-devicenet-eds-v100.zip](#)

[eaton-powerxl-da1-ethercat-esi-for-omron-v311.zip](#)

[eaton-powerxl-da1-ethernetip-eds-v150.zip](#)

[eaton-powerxl-da1-firmware-release-note-mz040041en-us.pdf](#)