

Specifications



Photo is representative



Eaton EP-400040

Eaton DA1 Variable frequency drive, 400 V AC, 3-phase, 5.8 A, 2.2 kW, IP66/NEMA 4X, Radio interference suppression filter, OLED display, Local controls, UV resistant

General specifications

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| PRODUCT NAME | Eaton DA1 Variable frequency drive |
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| CATALOG NUMBER | EP-400040 |
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| MODEL CODE | DA1-345D8FB-B6SO |
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| EAN | 4015082950224 |
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| PRODUCT LENGTH/DEPTH | 182 mm |
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| PRODUCT HEIGHT | 257 mm |
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| PRODUCT WIDTH | 188 mm |
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| PRODUCT WEIGHT | 3.5 kg |
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CE
Certified by UL for use in Canada
CSA-C22.2 No. 14
CUL
EAC
IEC/EN 61800-3
IEC/EN61800-3
IEC/EN61800-5
RCM
RoHS, ISO 9001
Safety: EN 61800-5-1: 2003

CERTIFICATIONS

Specification for general requirements: IEC/EN 61800-2
UkrSEPRO
UL
UL 508C
UL Category Control No.: NMMS, NMMS7
UL File No.: E172143
UL report applies to both US and Canada

CATALOG NOTES

The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake



Powering Business Worldwide

resistors and designs (e.g. different duty cycles) are available upon request.

General

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| CABLE LENGTH | 100 m, screened, maximum permissible, Motor feeder |
| | 150 m, unscreened, maximum permissible, Motor feeder |
| CABLE LENGTH | 200 m, screened, with motor choke, maximum permissible, Motor feeder |
| | 300 m, unscreened, with motor choke, maximum permissible, Motor feeder |
| CABLE LENGTH | C2 ≤ 5 m, Radio interference level, maximum motor cable length |
| | C3 ≤ 25 m, Radio interference level, maximum motor cable length |
| COMMUNICATION INTERFACE | CANopen®, built in EtherCAT, optional Ethernet IP, optional Modbus RTU, built in Modbus-TCP, optional OP-Bus (RS485), built in PROFIBUS, optional PROFINET, optional BACnet/IP, optional |
| CONNECTION TO SMARTWIRE-DT | No |
| DEGREE OF PROTECTION | IP66 NEMA 4X |
| ELECTROMAGNETIC COMPATIBILITY | 1st and 2nd environments (according to EN 61800-3) |
| FITTED WITH: | PC connection Control unit Breaking resistance Additional PCB protection Brake chopper IGBT inverter Internal DC link OLED display Radio interference suppression filter Local controls |
| FRAME SIZE | FS2 |
| FUNCTIONS | 4-quadrant operation possible |
| MOUNTING POSITION | Vertical |
| PRODUCT CATEGORY | Variable frequency drives |
| PROTECTION | Finger and back-of-hand proof, Protection against direct contact (BGV A3, |

Climatic environmental conditions

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| ALTITUDE | Max. 1000 m Above 1000 m with 1 % derating per 100 m Max. 4000 m |
| AMBIENT OPERATING TEMPERATURE - MIN | -10 °C |
| AMBIENT OPERATING TEMPERATURE - MAX | 40 °C |
| AMBIENT OPERATING TEMPERATURE AT 150% OVERLOAD - MIN | -10 °C |
| AMBIENT OPERATING TEMPERATURE AT 150% OVERLOAD - MAX | 40 °C |
| AMBIENT STORAGE TEMPERATURE - MIN | -40 °C |
| AMBIENT STORAGE TEMPERATURE - MAX | 60 °C |
| CLIMATIC PROOFING | < 95 average relative humidity (RH), no condensation, no corrosion |

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| | VBG4) |
| PROTOCOL | CAN EtherNet/IP MODBUS Other bus systems PROFIBUS PROFINET IO TCP/IP BACnet/IP |
| SAFETY FUNCTION/LEVEL | STO (Safe Torque Off, SIL3, PLe Cat 3) |
| SUITABLE FOR | Branch circuits, (UL/CSA) |
| RADIO INTERFERENCE CLASS | C1: for conducted emissions only Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments C2, C3: depending on the motor cable length, the connected load, and ambient conditions. |

Main circuit

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| EFFICIENCY | 95.4 % (η) |
| HEAT DISSIPATION AT CURRENT/SPEED | 51 W at 100% current and 0% speed 66 W at 100% current and 50% speed 81 W at 100% current and 90% speed 43 W at 50% current and 0% speed 47 W at 50% current and 50% speed 57 W at 50% current and 90% speed 38 W at 25% current and 50% speed 35 W at 25% current and 0% speed |
| INPUT CURRENT I_{LN} AT 150% OVERLOAD | 7.5 A |
| LEAKAGE CURRENT AT GROUND I_{PE} - MAX | 4.65 mA |
| MAINS SWITCH-ON FREQUENCY | Maximum of one time every 30 seconds |
| MAINS VOLTAGE - MIN | 342 V |
| MAINS VOLTAGE - MAX | 528 V |
| OPERATING MODE | Optional: Vector control with feedback (CLV) Sensorless vector control (SLV) Speed control with slip compensation U/f control |
| OUTPUT FREQUENCY - MIN | 0 Hz |
| OUTPUT FREQUENCY - MAX | 500 Hz |
| OUTPUT VOLTAGE (U₂) | 480 V AC, 3-phase 400 V AC, 3-phase |
| OVERLOAD CURRENT I_L AT 150% OVERLOAD | 8.7 A |
| RATED CONTROL SUPPLY VOLTAGE | 10 V DC (U _s , max. 10 mA) |
| RATED FREQUENCY - MIN | 48 Hz |
| RATED FREQUENCY - MAX | 62 Hz |
| RATED OPERATIONAL POWER AT 380/400 V, 50 HZ, 3-PHASE | 2.2 kW |
| RATED OPERATIONAL VOLTAGE | 480 V AC, 3-phase 400 V AC, 3-phase |
| RESOLUTION | 0.1 Hz (Frequency) |

Motor rating

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| ASSIGNED MOTOR CURRENT I_M AT 400 V, 50 HZ, 150% OVERLOAD | 5 A |
| ASSIGNED MOTOR CURRENT I_M AT 440 - 480 V, 60 HZ, 150% OVERLOAD | 4.8 A |
| ASSIGNED MOTOR POWER AT 460/480 V, 60 HZ, 3-PHASE | 3 HP |

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| | resolution, setpoint value) |
| SHORT-CIRCUIT PROTECTION RATING | 10 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring |
| STARTING CURRENT - MAX | 200 %, IH, max. starting current (High Overload), for 4 seconds every 40 seconds, Power section |
| SUPPLY FREQUENCY | 50/60 Hz |
| SWITCHING FREQUENCY | 8 kHz, 4 - 32 kHz adjustable (audible), fPWM, Power section, Main circuit |
| SYSTEM CONFIGURATION TYPE | AC supply systems with earthed center point |
| VOLTAGE RATING - MAX | 480 VAC |

Apparent power

APPARENT POWER AT 400 V 4.02 kVA

APPARENT POWER AT 480 V 4.82 kVA

Control circuit

NUMBER OF INPUTS (ANALOG) 2

NUMBER OF INPUTS (DIGITAL) 5

NUMBER OF OUTPUTS (ANALOG) 2

NUMBER OF OUTPUTS (DIGITAL) 2

NUMBER OF RELAY OUTPUTS 2 (parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1))

RATED CONTROL VOLTAGE (UC) 24 V DC (external, max. 100 mA)

Braking function

BRAKING RESISTANCE 150 Ω

BRAKING TORQUE Max. 30 % MN, Standard - Main circuit
Max. 100 % of rated operational current I_e , variable, DC - Main circuit
Max. 100 % of rated operational current I_e with external braking resistor - Main circuit

SWITCH-ON THRESHOLD FOR THE BRAKING TRANSISTOR 780 VDC

Design verification

EQUIPMENT HEAT DISSIPATION, CURRENT-DEPENDENT PVID 101.2 W

HEAT DISSIPATION CAPACITY PDISS 0 W

HEAT DISSIPATION PER POLE, CURRENT-DEPENDENT PVID 0 W

STATIC HEAT DISSIPATION, NON-CURRENT-DEPENDENT PVS 0 W

10.2.2 CORROSION RESISTANCE Meets the product standard's requirements.

10.2.3.1 VERIFICATION OF THERMAL STABILITY OF Meets the product standard's requirements.

| ENCLOSURES | |
|---|--|
| 10.2.3.2 VERIFICATION OF RESISTANCE OF INSULATING MATERIALS TO NORMAL HEAT | Meets the product standard's requirements. |
| 10.2.3.3 RESIST. OF INSUL. MAT. TO ABNORMAL HEAT/FIRE BY INTERNAL ELECT. EFFECTS | Meets the product standard's requirements. |
| 10.2.4 RESISTANCE TO ULTRA-VIOLET (UV) RADIATION | Meets the product standard's requirements. |
| 10.2.5 LIFTING | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 MECHANICAL IMPACT | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 INSCRIPTIONS | Meets the product standard's requirements. |
| 10.3 DEGREE OF PROTECTION OF ASSEMBLIES | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 CLEARANCES AND CREEPAGE DISTANCES | Meets the product standard's requirements. |
| 10.6 INCORPORATION OF SWITCHING DEVICES AND COMPONENTS | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 INTERNAL ELECTRICAL CIRCUITS AND CONNECTIONS | Is the panel builder's responsibility. |
| 10.8 CONNECTIONS FOR EXTERNAL CONDUCTORS | Is the panel builder's responsibility. |
| 10.9.2 POWER-FREQUENCY ELECTRIC STRENGTH | Is the panel builder's responsibility. |
| 10.9.3 IMPULSE WITHSTAND VOLTAGE | Is the panel builder's responsibility. |
| 10.9.4 TESTING OF ENCLOSURES MADE OF INSULATING MATERIAL | Is the panel builder's responsibility. |
| 10.10 TEMPERATURE RISE | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 SHORT-CIRCUIT RATING | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |

**10.12 ELECTROMAGNETIC
COMPATIBILITY**

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

**10.13 MECHANICAL
FUNCTION**

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Resources

3D MODELS

[eaton-EP-400016-3d-model.stp](#)

[eaton-EP-400016-drawing.dwg](#)

APPLICATION NOTES

[eaton-powerxl-da1-dc1-de1-system-bus-ap040022-en-us.pdf](#)

[eaton-powerxl-da1-dc1-db1-de1-rapidlink5-firmware-update-ap040214-en-us.pdf](#)

[eaton-powerxl-da1-starting-stopping-operation-ap040030-en-us.pdf](#)

[eaton-powerxl-da1-droop-function-ap040023-en-us.pdf](#)

[eaton-powerxl-da1-pid-controller-ap040025-en-us.pdf](#)

[eaton-powerxl-da1-pointer-to-parameter-ap040133-en-us.pdf](#)

[eaton-powerxl-da1-dc1-de1-internal-motor-protection-ap040016-en-us.pdf](#)

[Start, Stopp und Betrieb](#)

[eaton-powerxl-da1-use-of-multiple-ramps-ap040031-en-us.pdf](#)

[eaton-powerxl-da1-set-point-setting-ap040040-en-us.pdf](#)

[eaton-powerxl-vfd-dual-rating-ap040114-en-us.pdf](#)

[eaton-powerxl-da1-hoist-applications-ap040032-en-us.pdf](#)

[eaton-powerxl-da1-dc1-de1-conformal-coating-ap040182-en-us.pdf](#)

[eaton-powerxl-da1-i-o-configuration-ap040034-en-us.pdf](#)

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| | eaton-powerxl-dx-com-stick-3-ap040190-en-us.pdf eaton-powerxl-da1-master-slave-operation-ap040026-en-us.pdf eaton-powerxl-da1-operating-pm-bldc-motors-ap040051-en-us.pdf eaton-powerxl-da1-motor-vf-curves-induction-motors-ap040018-en-us.pdf eaton-powerxl-da1-vector-control-induction-motors-ap040028-en-us.pdf Electromagnetic compatibility (EMC) eaton-powerxl-da1-derating-ap040039-en-us.pdf |
| BROCHURES | eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-br040001en-en-us.pdf |
| CATALOGUES | Product Range Catalog Drives Engineering |
| DECLARATIONS OF CONFORMITY | eaton-variable-frequency-drive-declaration-of-conformity-uk251134en.pdf eaton-variable-frequency-drive-declaration-of-conformity-eu250651en.pdf |
| INSTALLATION INSTRUCTIONS | eaton-da1-variable-frequency-drive-il040061zu.pdf |
| INSTALLATION VIDEOS | Video PowerXL DA1 PowerXL Variable Frequency Drives DC1 and DA1 - EN |
| MANUALS AND USER GUIDES | eaton-da1-variable-frequency-drive-mn040063-en-us.pdf |
| MULTIMEDIA | System solutions based on EtherCAT |

[Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments?](#)

[eaton-powerxl-dx-comstick3-ble-drivers.zip](#)

[eaton-powerxl-dx-cbl-pc-3m0-usb-driver.zip](#)

[eaton-powerxl-da1-profinet-tia-v12-library.zip](#)

[eaton-powerxl-da1-profibus-gsd-v216.zip](#)

[eaton-powerxl-da1-canopen-eds-v250.zip](#)

[eaton-powerxl-dx-cbl-pc-1m5-usb-driver.zip](#)

[eaton-powerxl-da1-profinet-gsdml-v226.zip](#)

[eaton-powerxl-da1-swd-codesys-v3-library.zip](#)

SOFTWARE, FIRMWARE,
AND APPLICATIONS

[eaton-powerxl-pcsoftware-drivesconnect-v1501.zip](#)

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[eaton-powerxl-da1-firmware-release-note-mz040041en-us.pdf](#)

[eaton-powerxl-da1-ethernetip-eds-v150.zip](#)

[eaton-powerxl-da1-devicenet-eds-v100.zip](#)

[eaton-powerxl-da1-ethercat-esi-for-omron-v311.zip](#)

PROJECT NAME:

PROJECT NUMBER:

PREPARED BY:

DATE:



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