

Specifications



Photo is representative



Eaton EP-400024

Eaton DA1 Variable frequency drive, 230 V AC, 3-phase, 7 A, 1.5 kW, IP66/NEMA 4X, Radio interference suppression filter, OLED display, Local controls, UV resistant

General specifications

| | |
|-----------------------------|------------------------------------|
| PRODUCT NAME | Eaton DA1 Variable frequency drive |
| CATALOG NUMBER | EP-400024 |
| MODEL CODE | DA1-327D0FB-B6SO |
| EAN | 4015082950064 |
| PRODUCT LENGTH/DEPTH | 182 mm |
| PRODUCT HEIGHT | 257 mm |
| PRODUCT WIDTH | 188 mm |
| PRODUCT WEIGHT | 3.5 kg |

CE
Certified by UL for use in
Canada
CSA-C22.2 No. 14
CUL
EAC
IEC/EN 61800-3
IEC/EN61800-3
IEC/EN61800-5
RCM
RoHS, ISO 9001
Safety: EN 61800-5-1: 2003

CERTIFICATIONS

Specification for general
requirements: IEC/EN
61800-2
UkrSEPRO
UL
UL 508C
UL Category Control No.:
NMMS, NMMS7
UL File No.: E172143
UL report applies to both
US and Canada

CATALOG NOTES

The brake resistors are
assigned based on the
maximum rated power of
the variable frequency
drive. Additional brake

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resistors and designs (e.g. different duty cycles) are available upon request.

General

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| CABLE LENGTH | 100 m, screened, maximum permissible, Motor feeder |
| | 150 m, unscreened, maximum permissible, Motor feeder |
| CABLE LENGTH | 200 m, screened, with motor choke, maximum permissible, Motor feeder |
| | 300 m, unscreened, with motor choke, maximum permissible, Motor feeder |
| CABLE LENGTH | C2 ≤ 5 m, Radio interference level, maximum motor cable length |
| | C3 ≤ 25 m, Radio interference level, maximum motor cable length |
| COMMUNICATION INTERFACE | CANopen®, built in EtherCAT, optional Ethernet IP, optional Modbus RTU, built in Modbus-TCP, optional OP-Bus (RS485), built in PROFIBUS, optional PROFINET, optional BACnet/IP, optional |
| CONNECTION TO SMARTWIRE-DT | No |
| DEGREE OF PROTECTION | IP66 NEMA 4X |
| ELECTROMAGNETIC COMPATIBILITY | 1st and 2nd environments (according to EN 61800-3) |
| FITTED WITH: | PC connection Control unit Breaking resistance Additional PCB protection Brake chopper IGBT inverter Internal DC link OLED display Radio interference suppression filter Local controls |
| FRAME SIZE | FS2 |
| FUNCTIONS | 4-quadrant operation possible |
| MOUNTING POSITION | Vertical |
| PRODUCT CATEGORY | Variable frequency drives |
| PROTECTION | Finger and back-of-hand proof, Protection against direct contact (BGV A3, |

Climatic environmental conditions

| | |
|---|--|
| ALTITUDE | Max. 1000 m Above 1000 m with 1 % derating per 100 m Max. 4000 m |
| AMBIENT OPERATING TEMPERATURE - MIN | -10 °C |
| AMBIENT OPERATING TEMPERATURE - MAX | 40 °C |
| AMBIENT OPERATING TEMPERATURE AT 150% OVERLOAD - MIN | -10 °C |
| AMBIENT OPERATING TEMPERATURE AT 150% OVERLOAD - MAX | 40 °C |
| AMBIENT STORAGE TEMPERATURE - MIN | -40 °C |
| AMBIENT STORAGE TEMPERATURE - MAX | 60 °C |
| CLIMATIC PROOFING | < 95 average relative humidity (RH), no condensation, no corrosion |

| | |
|---------------------------------|--|
| | VBG4) |
| PROTOCOL | CAN EtherNet/IP MODBUS Other bus systems PROFIBUS PROFINET IO TCP/IP BACnet/IP |
| SAFETY FUNCTION/LEVEL | STO (Safe Torque Off, SIL3, PLe Cat 3) |
| SUITABLE FOR | Branch circuits, (UL/CSA) |
| RADIO INTERFERENCE CLASS | C1: for conducted emissions only Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments C2, C3: depending on the motor cable length, the connected load, and ambient conditions. |

Main circuit

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| EFFICIENCY | 95.9 % (η) |
| HEAT DISSIPATION AT CURRENT/SPEED | 51 W at 100% current and 0% speed 60 W at 100% current and 50% speed 71 W at 100% current and 90% speed 36 W at 50% current and 0% speed 43 W at 50% current and 50% speed 51 W at 50% current and 90% speed 35 W at 25% current and 50% speed 31 W at 25% current and 0% speed |
| INPUT CURRENT I_{LN} AT 150% OVERLOAD | 10.5 A |
| LEAKAGE CURRENT AT GROUND I_{PE} - MAX | 1.73 mA |
| MAINS SWITCH-ON FREQUENCY | Maximum of one time every 30 seconds |
| MAINS VOLTAGE - MIN | 180 V |
| MAINS VOLTAGE - MAX | 264 V |
| OPERATING MODE | Optional: Vector control with feedback (CLV) Sensorless vector control (SLV) Speed control with slip compensation U/f control |
| OUTPUT FREQUENCY - MIN | 0 Hz |
| OUTPUT FREQUENCY - MAX | 500 Hz |
| OUTPUT VOLTAGE (U₂) | 230 V AC, 3-phase 240 V AC, 3-phase |
| OVERLOAD CURRENT I_L AT 150% OVERLOAD | 10.5 A |
| RATED CONTROL SUPPLY VOLTAGE | 10 V DC (U _s , max. 10 mA) |
| RATED FREQUENCY - MIN | 48 Hz |
| RATED FREQUENCY - MAX | 62 Hz |
| RATED OPERATIONAL POWER AT 220/230 V, 50 HZ, 1-PHASE | 1.5 kW |
| RATED OPERATIONAL VOLTAGE | 230 V AC, 3-phase 240 V AC, 3-phase |
| RESOLUTION | 0.1 Hz (Frequency) |

Motor rating

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|--|-------|
| ASSIGNED MOTOR CURRENT I_M AT 220 - 240 V, 60 HZ, 150% OVERLOAD | 6.8 A |
| ASSIGNED MOTOR CURRENT I_M AT 230 V, 50 HZ, 150% OVERLOAD | 6.3 A |
| ASSIGNED MOTOR POWER AT 230/240 V, 60 HZ, 1-PHASE | 2 HP |

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| | resolution, setpoint value) |
| SHORT-CIRCUIT PROTECTION RATING | 15 A, UL (Class CC or J), Safety device (fuse or miniature circuit-breaker), Power Wiring |
| STARTING CURRENT - MAX | 200 %, IH, max. starting current (High Overload), for 4 seconds every 40 seconds, Power section |
| SUPPLY FREQUENCY | 50/60 Hz |
| SWITCHING FREQUENCY | 16 kHz, 4 - 32 kHz adjustable (audible), fPWM, Power section, Main circuit |
| SYSTEM CONFIGURATION TYPE | AC supply systems with earthed center point |
| VOLTAGE RATING - MAX | 240 VAC |

Apparent power

APPARENT POWER AT 230 V 2.79 kVA

APPARENT POWER AT 240 V 2.91 kVA

Control circuit

NUMBER OF INPUTS (ANALOG) 2

NUMBER OF INPUTS (DIGITAL) 5

NUMBER OF OUTPUTS (ANALOG) 2

NUMBER OF OUTPUTS (DIGITAL) 2

NUMBER OF RELAY OUTPUTS 2 (parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1))

RATED CONTROL VOLTAGE (UC) 24 V DC (external, max. 100 mA)

Braking function

BRAKING RESISTANCE 50 Ω

BRAKING TORQUE Max. 30 % MN, Standard - Main circuit
Max. 100 % of rated operational current I_e , variable, DC - Main circuit
Max. 100 % of rated operational current I_e with external braking resistor - Main circuit

SWITCH-ON THRESHOLD FOR THE BRAKING TRANSISTOR 390 VDC

Design verification

EQUIPMENT HEAT DISSIPATION, CURRENT-DEPENDENT PVID 61.5 W

HEAT DISSIPATION CAPACITY PDISS 0 W

HEAT DISSIPATION PER POLE, CURRENT-DEPENDENT PVID 0 W

STATIC HEAT DISSIPATION, NON-CURRENT-DEPENDENT PVS 0 W

10.2.2 CORROSION RESISTANCE Meets the product standard's requirements.

10.2.3.1 VERIFICATION OF THERMAL STABILITY OF Meets the product standard's requirements.

| ENCLOSURES | |
|---|--|
| 10.2.3.2 VERIFICATION OF RESISTANCE OF INSULATING MATERIALS TO NORMAL HEAT | Meets the product standard's requirements. |
| 10.2.3.3 RESIST. OF INSUL. MAT. TO ABNORMAL HEAT/FIRE BY INTERNAL ELECT. EFFECTS | Meets the product standard's requirements. |
| 10.2.4 RESISTANCE TO ULTRA-VIOLET (UV) RADIATION | Meets the product standard's requirements. |
| 10.2.5 LIFTING | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 MECHANICAL IMPACT | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 INSCRIPTIONS | Meets the product standard's requirements. |
| 10.3 DEGREE OF PROTECTION OF ASSEMBLIES | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 CLEARANCES AND CREEPAGE DISTANCES | Meets the product standard's requirements. |
| 10.6 INCORPORATION OF SWITCHING DEVICES AND COMPONENTS | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 INTERNAL ELECTRICAL CIRCUITS AND CONNECTIONS | Is the panel builder's responsibility. |
| 10.8 CONNECTIONS FOR EXTERNAL CONDUCTORS | Is the panel builder's responsibility. |
| 10.9.2 POWER-FREQUENCY ELECTRIC STRENGTH | Is the panel builder's responsibility. |
| 10.9.3 IMPULSE WITHSTAND VOLTAGE | Is the panel builder's responsibility. |
| 10.9.4 TESTING OF ENCLOSURES MADE OF INSULATING MATERIAL | Is the panel builder's responsibility. |
| 10.10 TEMPERATURE RISE | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 SHORT-CIRCUIT RATING | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |

**10.12 ELECTROMAGNETIC
COMPATIBILITY**

Is the panel builder's responsibility. The specifications for the switchgear must be observed.

**10.13 MECHANICAL
FUNCTION**

The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Resources

3D MODELS

[eaton-EP-400016-drawing.dwg](#)

[eaton-EP-400016-3d-model.stp](#)

[eaton-powerxl-da1-vector-control-induction-motors-ap040028-en-us.pdf](#)

[eaton-powerxl-da1-derating-ap040039-en-us.pdf](#)

[eaton-powerxl-da1-motor-vf-curves-induction-motors-ap040018-en-us.pdf](#)

[eaton-powerxl-da1-i-o-configuration-ap040034-en-us.pdf](#)

[Electromagnetic compatibility \(EMC\)](#)

[eaton-powerxl-vfd-dual-rating-ap040114-en-us.pdf](#)

[eaton-powerxl-da1-dc1-de1-conformal-coating-ap040182-en-us.pdf](#)

APPLICATION NOTES

[eaton-powerxl-da1-hoist-applications-ap040032-en-us.pdf](#)

[eaton-powerxl-da1-pid-controller-ap040025-en-us.pdf](#)

[eaton-powerxl-da1-pointer-to-parameter-ap040133-en-us.pdf](#)

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[eaton-powerxl-dx-com-stick-3-ap040190-en-us.pdf](#)

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| | eaton-powerxl-da1-master-slave-operation-ap040026-en-us.pdf eaton-powerxl-da1-dc1-db1-de1-rapidlink5-firmware-update-ap040214-en-us.pdf eaton-powerxl-da1-starting-stopping-operation-ap040030-en-us.pdf eaton-powerxl-da1-dc1-de1-system-bus-ap040022-en-us.pdf eaton-powerxl-da1-dc1-de1-internal-motor-protection-ap040016-en-us.pdf Start, Stopp und Betrieb eaton-powerxl-da1-droop-function-ap040023-en-us.pdf |
| BROCHURES | eaton-powerxl-variable-frequency-drives-dc1-da1-brochure-br040001en-en-us.pdf |
| CATALOGUES | Product Range Catalog Drives Engineering |
| DECLARATIONS OF CONFORMITY | eaton-variable-frequency-drive-declaration-of-conformity-eu250651en.pdf eaton-variable-frequency-drive-declaration-of-conformity-uk251134en.pdf |
| INSTALLATION INSTRUCTIONS | eaton-da1-variable-frequency-drive-il040061zu.pdf |
| INSTALLATION VIDEOS | Video PowerXL DA1 PowerXL Variable Frequency Drives DC1 and DA1 - EN |
| MANUALS AND USER GUIDES | eaton-da1-variable-frequency-drive-mn040063-en-us.pdf |
| MULTIMEDIA | Looking for variable frequency drives DC1 and DA1 which can be used in harsh environments? |

[System solutions based on EtherCAT](#)

[eaton-powerxl-da1-devicenet-eds-v100.zip](#)

[eaton-powerxl-da1-firmware-release-note-mz040041en-us.pdf](#)

[eaton-powerxl-da1-canopen-codesys-v3-library.zip](#)

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[eaton-powerxl-da1-profinet-gsdml-v226.zip](#)

[eaton-powerxl-dx-cbl-pc-1m5-usb-driver.zip](#)

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[eaton-powerxl-da1-canopen-eds-v250.zip](#)

[eaton-powerxl-da1-ethercat-esi-v310.zip](#)

SOFTWARE, FIRMWARE,
AND APPLICATIONS

PROJECT NAME:

PROJECT NUMBER:

PREPARED BY:

DATE:



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