

# Variable Frequency Drive, 1-/3-phase 230 V, 7.0 A, 1.5 kW, Vector control, EMC-Filter, Brake-Chopper



Part no. DA1-127D0FB-B6SC Article no. 169350 Catalog No. DA1-127D0FB-B6SC

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|  |        |  |  |

| Delivery program                   |                |    |   |
|------------------------------------|----------------|----|---|
| Product range                      |                |    | Variable frequency drives   |
| Part group reference (e.g. DIL)    |                |    | DA1   |
| Rated operational voltage          | U <sub>e</sub> |    | 230 V AC, 1-phase<br>240 V AC, single-phase   |
| Output voltage with V <sub>e</sub> | U <sub>2</sub> |    | 230 V AC, 3-phase<br>240 V AC, 3-phase  |
| Mains voltage (50/60Hz)            | $U_{LN}$       | V  | 200 (-10%) - 240 (+10%)   |
| Rated operational current          |                |    |   |
| At 150% overload                   | I <sub>e</sub> | Α  | 7   |
| Note                               |                |    | Rated operational current at a switching frequency of 16 kHz and an ambient air temperature of +40 $^{\circ}\text{C}$                               |
| Note                               |                |    | Overload cycle for 60 s every 600 s   |
| Assigned motor rating              |                |    |   |
| Note                               |                |    | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm $^{-1}$ at 50 Hz or 1800 min $^{-1}$ at 60 Hz |
| Note                               |                |    | Overload cycle for 60 s every 600 s   |
| Note                               |                |    | at 230 V, 50 Hz   |
| 150 % Overload                     | Р              | kW | 1.5   |
| 150 % Overload                     | I <sub>M</sub> | Α  | 6.3   |
| Note                               |                |    | at 220 - 240 V, 60 Hz   |
| 150 % Overload                     | P              | HP | 2   |
| 150 % Overload                     | I <sub>M</sub> | Α  | 6.8   |
| Degree of Protection               |                |    | IP66/NEMA 4X  |
| Interface/field bus (built-in)     |                |    | OP-Bus (RS485)/Modbus RTU, CANopen®   |
| Fieldbus connection (optional)     |                |    | Ethernet IP DeviceNet PROFIBUS PROFINET Modbus-TCP EtherCAT   |
| Fitted with                        |                |    | Radio interference suppression filter Brake chopper Additional PCB protection OLED display Local controls   |
| Frame size                         |                |    | FS2   |
| Connection to SmartWire-DT         |                |    | with SmartWire-DT module DX-NET-SWD2  |
|                                    |                |    |   |

## Technical data

| General                        |                   |    |   |
|--------------------------------|-------------------|----|---|
| Standards                      |                   |    | Specification for general requirements: IEC/EN 61800-2<br>EMC requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5-1                                       |
| Certifications                 |                   |    | CE, UL, cUL, c-Tick, UkrSepro, EAC  |
| Production quality             |                   |    | RoHS, ISO 9001  |
| Climatic proofing              | $\rho_{\text{W}}$ | %  | < 95%, average relative humidity (RH), non-condensing, non-corrosive  |
| Ambient temperature            |                   |    |   |
| operation (150 % overload)     | 9                 | °C | -10 - +40   |
| Storage                        | 9                 | °C | -40 - +60   |
| Radio interference level       |                   |    |   |
| Radio interference class (EMC) |                   |    | C1, C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |

| Faringament (FMC)   |                  |     | 1at and find antivarments on as TALC1000.0  |
|---|------------------|-----|---|
| Environment (EMC)   |                  |     | 1st and 2nd environments as per EN 61800-3  |
| maximum motor cable length  |                  | m   | C1 ≤ 1 m<br>C2 ≤ 5 m<br>C3 ≤ 25 m   |
| Mounting position   |                  |     | Vertical  |
| Altitude  |                  | m   | 0 - 1000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 4000 m  |
| Degree of Protection  |                  |     | IP66/NEMA 4X  |
| Protection against direct contact                                   |                  |     | BGV A3 (VBG4, finger- and back-of-hand proof)   |
| Main circuit  |                  |     |   |
| Supply  |                  |     |   |
| Rated operational voltage   | U <sub>e</sub>   |     | 230 V AC, 1-phase<br>240 V AC, single-phase   |
| Mains voltage (50/60Hz)   | U <sub>LN</sub>  | V   | 200 (-10%) - 240 (+10%)   |
| Input current (150% overload)                                       | I <sub>LN</sub>  | Α   | 12.9  |
| System configuration  |                  |     | AC supply systems with earthed center point   |
| Supply frequency  | $f_{LN}$         | Hz  | 50/60   |
| Frequency range   | $f_{LN}$         | Hz  | 48 - 62   |
| Mains switch-on frequency   |                  |     | Maximum of one time every 30 seconds  |
| Power section   |                  |     |   |
| Function  |                  |     | Frequency inverter with internal DC link and IGBT inverter  |
| Overload current (150% overload)                                    | IL               | Α   | 10.5  |
| max. starting current (High Overload)                               | I <sub>H</sub>   | %   | 200   |
| Note about max. starting current                                    |                  |     | for 4 seconds every 40 seconds  |
| Output voltage with V <sub>e</sub>                                  | U <sub>2</sub>   |     | 230 V AC, 3-phase   |
|   |                  |     | 240 V AC, 3-phase   |
| Output Frequency  | f <sub>2</sub>   | Hz  | 0 - 50/60 (max. 500)  |
| Switching frequency   | f <sub>PWM</sub> | kHz | 16<br>adjustable 4 - 32 (audible)   |
| Operation Mode  |                  |     | U/f control Speed control with slip compensation sensorless vector control (SLV) optional: Vector control with feedback (CLV)                                   |
| Frequency resolution (setpoint value)                               | Δf               | Hz  | 0.1   |
| Rated operational current   |                  |     |   |
| At 150% overload  | le               | Α   | 7   |
| Note  |                  |     | Rated operational current at a switching frequency of 16 kHz and an ambient air temperature of +40 $^{\circ}\text{C}$   |
| Power loss  |                  |     |   |
| Heat dissipation at rated operational current $\rm I_{e}$ =150 $\%$ | $P_{V}$          | W   | 63  |
| Efficiency  | η                | %   | 95.8  |
| Maximum leakage current to ground (PE) without motor                | I <sub>PE</sub>  | mA  | 2.49  |
| Fitted with   |                  |     | Radio interference suppression filter Brake chopper Additional PCB protection OLED display Local controls   |
| Safety function   |                  |     | STO (Safe Torque Off, SIL1, PLc Cat 1)  |
| Frame size  |                  |     | FS2   |
| Motor feeder  |                  |     |   |
| Note  |                  |     | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz |
| Note  |                  |     | Overload cycle for 60 s every 600 s   |
| Note  |                  |     | at 230 V, 50 Hz   |
| 150 % Overload  | P                | kW  | 1.5   |
| Note  |                  |     | at 220 - 240 V, 60 Hz   |
| 150 % Overload  | P                | НР  | 2   |
| maximum permissible cable length                                    | l                | m   | screened: 100<br>screened, with motor choke: 200<br>unscreened: 150<br>unscreened, with motor choke: 300  |
|   |                  |     |   |

| Apparent power                                    |                  |     |  |
|---|------------------|-----|--|
| Apparent power at rated operation 230 V           | S                | kVA | 2.79   |
| Apparent power at rated operation 240 V           | S                | kVA | 2.91   |
| Braking function                                  |                  |     |  |
| Standard braking torque                           |                  |     | max. 30 % M <sub>N</sub>   |
| DC braking torque                                 |                  |     | adjustable to 100 %  |
| Braking torque with external braking resistance   |                  |     | Max. 100% of rated operational current I <sub>e</sub> with external braking resistor     |
| minimum external braking resistance               | R <sub>min</sub> | Ω   | 50   |
| Switch-on threshold for the braking transistor    | U <sub>DC</sub>  | V   | 390 V DC   |
| Control section                                   |                  |     |  |
| External control voltage                          | U <sub>c</sub>   | V   | 24 V DC (max. 100 mA)  |
| Reference voltage                                 | $U_s$            | V   | 10 V DC (max. 10 mA)   |
| Analog inputs                                     |                  |     | 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA   |
| Analog outputs                                    |                  |     | 2, parameterizable, 0 - 10 V, 0/4 - 20 mA  |
| Digital inputs                                    |                  |     | 3, parameterizable, max. 30 VDC, max. 5 for non-parameterized analog inputs              |
| Digital outputs                                   |                  |     | 2, parameterizable, 24 V DC  |
| Relay outputs                                     |                  |     | 2, parameterizable, 1 N/O and 1 changeover contact, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) |
| Interface/field bus (built-in)                    |                  |     | OP-Bus (RS485)/Modbus RTU, CANopen®  |
| Assigned switching and protective elements        |                  |     |  |
| Power Wiring                                      |                  |     |  |
| Safety device (fuse or miniature circuit-breaker) |                  |     |  |
| IEC (Type B, gG), 150 %                           |                  |     | FAZ-B20/1N   |
| UL (Class CC or J)                                |                  | Α   | 20   |
| Mains contactor                                   |                  |     |  |
| 150 % overload (CT/I $_{\rm H}$ , at 50 °C)       |                  |     | DILM7  |
| Main choke  |                  |     |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)     |                  |     | DX-LN1-018   |
| DC link connection                                |                  |     |  |
| Braking resistance                                |                  |     |  |
| 10 % Einschaltdauer (ED)                          |                  |     | DX-BR050-0K4   |
| 20 % duty factor (DF)                             |                  |     | DX-BR050-0K8   |
|   |                  |     |  |

## Design verification as per IEC/EN 61439

| boolgii tormoution do por 120/211 or 100  |                   |    |  |
|---|-------------------|----|--|
| Technical data for design verification  |                   |    |  |
| Rated operational current for specified heat dissipation  | In                | Α  | 7  |
| Heat dissipation per pole, current-dependent  | P <sub>vid</sub>  | W  | 0  |
| Equipment heat dissipation, current-dependent   | P <sub>vid</sub>  | W  | 63   |
| Static heat dissipation, non-current-dependent  | $P_{vs}$          | W  | 0  |
| Heat dissipation capacity   | P <sub>diss</sub> | W  | 0  |
| Operating ambient temperature min.  |                   | °C | -10  |
| Operating ambient temperature max.  |                   | °C | 40   |
| IEC/EN 61439 design verification  |                   |    |  |
| 10.2 Strength of materials and parts  |                   |    |  |
| 10.2.2 Corrosion resistance   |                   |    | Meets the product standard's requirements.                         |
| 10.2.3.1 Verification of thermal stability of enclosures  |                   |    | Meets the product standard's requirements.                         |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat  |                   |    | Meets the product standard's requirements.                         |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects $$ |                   |    | Meets the product standard's requirements.                         |
| 10.2.4 Resistance to ultra-violet (UV) radiation  |                   |    | Meets the product standard's requirements.                         |
| 10.2.5 Lifting  |                   |    | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 Mechanical impact  |                   |    | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 Inscriptions   |                   |    | Meets the product standard's requirements.                         |
| 10.3 Degree of protection of ASSEMBLIES   |                   |    | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 Clearances and creepage distances  |                   |    | Meets the product standard's requirements.                         |

| 10.5 Protection against electric shock                   | Does not apply, since the entire switchgear needs to be evaluated.   |
|--|--|
| 10.6 Incorporation of switching devices and components   | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.7 Internal electrical circuits and connections        | Is the panel builder's responsibility.   |
| 10.8 Connections for external conductors                 | Is the panel builder's responsibility.   |
| 10.9 Insulation properties                               |  |
| 10.9.2 Power-frequency electric strength                 | Is the panel builder's responsibility.   |
| 10.9.3 Impulse withstand voltage                         | Is the panel builder's responsibility.   |
| 10.9.4 Testing of enclosures made of insulating material | Is the panel builder's responsibility.   |
| 10.10 Temperature rise                                   | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating                               | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.12 Electromagnetic compatibility                      | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.13 Mechanical function                                | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.                         |

## **Technical data ETIM 6.0**

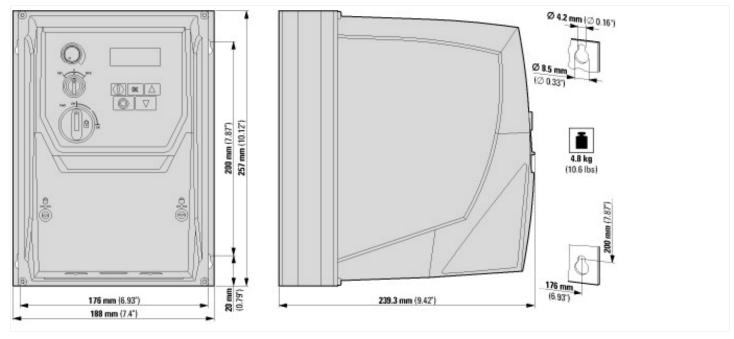
| Electric engineering, automation, process control engineering / Electrical driv | ve / Static frequency conver | ter / Static frequency converter = < 1 kv (ecl@ss8.1-27-02-31-01 [AKE177011]) |
|---|------------------------------|---|
| Mains voltage   | V                            | 200 - 240   |
| Mains frequency   |                              | 50/60 Hz  |
| Number of phases input  |                              | 1   |
| Number of phases output   |                              | 3   |
| Max. output frequency   | Hz                           | 500   |
| Max. output voltage   | V                            | 230   |
| Rated output current I2N  | Α                            | 7   |
| Max. output at quadratic load at rated output voltage                           | kW                           | 1.5   |
| Max. output at linear load at rated output voltage                              | kW                           | 1.5   |
| With control unit   |                              | Yes   |
| Application in industrial area permitted  |                              | Yes   |
| Application in domestic- and commercial area permitted                          |                              | Yes   |
| Supporting protocol for TCP/IP  |                              | No  |
| Supporting protocol for PROFIBUS  |                              | Yes   |
| Supporting protocol for CAN   |                              | Yes   |
| Supporting protocol for INTERBUS  |                              | No  |
| Supporting protocol for ASI   |                              | No  |
| Supporting protocol for KNX   |                              | No  |
| Supporting protocol for MODBUS  |                              | Yes   |
| Supporting protocol for Data-Highway  |                              | No  |
| Supporting protocol for DeviceNet   |                              | No  |
| Supporting protocol for SUCONET   |                              | No  |
| Supporting protocol for LON   |                              | No  |
| Supporting protocol for PROFINET IO   |                              | Yes   |
| Supporting protocol for PROFINET CBA  |                              | No  |
| Supporting protocol for SERCOS  |                              | No  |
| Supporting protocol for Foundation Fieldbus                                     |                              | No  |
| Supporting protocol for EtherNet/IP   |                              | Yes   |
| Supporting protocol for AS-Interface Safety at Work                             |                              | No  |
| Supporting protocol for DeviceNet Safety  |                              | No  |
| Supporting protocol for INTERBUS-Safety   |                              | No  |
| Supporting protocol for PROFIsafe   |                              | No  |
| Supporting protocol for SafetyBUS p   |                              | No  |
| Supporting protocol for other bus systems                                       |                              | No  |
| Number of HW-interfaces industrial Ethernet                                     |                              | 0   |
| Number of HW-interfaces PROFINET  |                              | 0   |
| Number of HW-interfaces RS-232  |                              | 0   |

| Number of HW-interfaces RS-422             |    | 0           |
|--|----|-------------|
| Number of HW-interfaces RS-485             |    | 1           |
| Number of HW-interfaces serial TTY         |    | 0           |
| Number of HW-interfaces USB                |    | 1           |
| Number of HW-interfaces parallel           |    | 0           |
| Number of HW-interfaces other              |    | 0           |
| With optical interface                     |    | No          |
| With PC connection                         |    | Yes         |
| Integrated breaking resistance             |    | Yes         |
| 4-quadrant operation possible              |    | No          |
| Type of converter                          |    | U converter |
| Degree of protection (IP)                  |    | IP66        |
| Height                                     | mm | 231         |
| Width                                      | mm | 107         |
| Depth                                      | mm | 186         |
| Relative symmetric net frequency tolerance | %  | 5           |
| Relative symmetric net current tolerance   | %  | 10          |

### **Approvals**

| Product Standards                    | UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking |
|--------------------------------------|---|
| UL File No.                          | E172143   |
| UL Category Control No.              | NMMS, NMMS7   |
| CSA File No.                         | UL report applies to both US and Canada                             |
| North America Certification          | UL listed, certified by UL for use in Canada                        |
| Specially designed for North America | No  |
| Suitable for                         | Branch circuits   |
| Max. Voltage Rating                  | 1~ 240 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)            |
| Degree of Protection                 | IEC: IP66   |

### **Dimensions**



### **Additional product information (links)**

IL04020015Z DA1 variable frequency drives (FS2+3, IP66)

IL04020015Z DA1 variable frequency drives (FS2+3, IP66)

ftp://ftp.moeller.net/DOCUMENTATION/AWA\_INSTRUCTIONS/IL04020015Z2013\_08.pdf

MN04020005Z DA1 variable frequency drives, Installation manual

MN04020005Z Frequenzumrichter DA1, Handbuch - Deutsch ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020005Z\_DE.pdf

| MN04020005Z DA1 variable frequency drive, manual - English   | ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020005Z_EN.pdf                                     |
|--|--|
| MN04020006Z DA1 variable frequency drives,   | Parameters manual  |
| MN04020006Z DA1 variable frequency drives, Parameters manual - Deutsch                                   | ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020006Z_DE.pdf                                     |
| MN04020006Z DA1 variable frequency drives,<br>Parameters manual - English                                | ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020006Z_EN.pdf                                     |
| CA04020001Z-DE Sortimentskatalog:<br>Antriebstechnik effizient gestalten, Motoren<br>starten und steuern | http://www.eaton.eu/DE/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct_1095238_de.pdf |